

Consider two vector spaces V, W (over the same field F). A function $T: V \rightarrow W$ is called a linear map (transformation) if

- i) $T(v+w) = T(v) + T(w)$ for all $v, w \in V$
- ii) $T(k \cdot v) = k \cdot T(v)$ for all $v \in V$ and $k \in F$

Of course, then we define

$$\begin{aligned} \text{Im}(T) &= \{ u \in W \mid \exists v \in V, T(v) = u \} \\ &= \{ T(v) \mid v \in V \} \end{aligned}$$

and

$$\text{Ker}(T) = \{ v \in V \mid T(v) = 0 \}$$

That is, $\text{Ker}(T) \subseteq V$ and $\text{Im}(T) \subseteq W$ are subspaces. (check this.)

If the space $\text{Im}(T)$ is finite dimensional, then $\dim(\text{Im}(T))$ is called **rank** of T , and if $\text{Ker}(T)$ is finite dimensional, $\dim(\text{Ker}(T))$ is called **nullity** of T .

Theorem: Say V, W are vector spaces and V is finite dimensional. Let $T: V \rightarrow W$ be a linear map. Then:

$$\dim(V) = \text{rank}(T) + \text{nullity}(T) = \dim(\text{Im}(T)) + \dim(\text{Ker}(T)).$$

Proof: Exactly the same as for \mathbb{R}^n . **Exercise!**

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Warning: This only works (and makes sense) for finite dimensional V .

Example: 1) Left translation: let V be a space of all infinite sequences of, say, complex numbers (we can also take sequences of any other field, like \mathbb{R} , \mathbb{Q} , \mathbb{Z} etc.). Consider the map

$$L: V \rightarrow V \\ (z_0, z_1, z_2, \dots) \mapsto (z_1, z_2, z_3, z_4, \dots)$$

L is a linear transformation:

$$L((z_0, z_1, \dots) + (w_0, w_1, \dots)) = L((z_0 + w_0, z_1 + w_1, \dots)) = \\ = (z_1 + w_1, z_2 + w_2, \dots) = L((z_0, z_1, \dots)) + L((w_0, w_1, \dots))$$

$$L(\lambda(z_0, z_1, z_2, \dots)) = L((\lambda z_0, \lambda z_1, \dots)) = (\lambda z_1, \lambda z_2, \dots) \\ = \lambda L((z_0, z_1, \dots))$$

$\text{Ker } L$:

$$L((z_0, z_1, \dots)) = 0_V = (0, 0, \dots) \Rightarrow (z_1, z_2, z_3, \dots) = (0, 0, \dots) \\ \Rightarrow z_i = 0 \text{ for } i = 1, 2, \dots. \text{ Therefore}$$

$$\text{Ker } L = \{ (z_0, 0, 0, 0, \dots) \in V \mid z_0 \in \mathbb{C} \} \text{ and} \\ \text{nullity}(L) = 1, \text{ since } (1, 0, 0, \dots) \text{ is a basis of } \text{Ker } L.$$

$\text{Im } L$: For any sequence (z_0, z_1, z_2, \dots) we have that, for example, $L((0, z_0, z_1, z_2, \dots)) = (z_0, z_1, z_2, \dots)$

that, for example, $U((0, z_0, z_1, z_2, \dots)) = (z_0, z_1, z_2, \dots)$

therefore any sequence is in the image of U . So, $\text{Im}(U) = V$

2) Let $C[0,1]$ denote the vector space of all continuous functions from closed interval $[0,1]$ to real numbers \mathbb{R} . Define a map

$$I: C[0,1] \rightarrow \mathbb{R}$$
$$f \mapsto \int_0^1 f(x) dx$$

I is linear:

$$I(f+g) = \int_0^1 (f(x)+g(x)) dx = \int_0^1 f(x) dx + \int_0^1 g(x) dx = I(f) + I(g)$$

$$I(c \cdot f) = \int_0^1 c f(x) dx = c \int_0^1 f(x) dx = c \cdot I(f).$$

$\text{Im } I$:

$b \in \text{Im}(I)$ if and only if there exists a function $f \in C[0,1]$, such that $\int_0^1 f(x) dx = b$. One may possibly just choose $f(x) = b$, therefore $\text{Im } I = \mathbb{R}$.

$\text{Ker } I$:

$$f \in \text{Ker } I \iff \int_0^1 f(x) dx = 0, \text{ so } \text{Ker } I = \{f \in C[0,1] \mid \int_0^1 f(x) dx = 0\}$$

3) Let $\text{Mat}_{2 \times 2}(\mathbb{R}) \xrightarrow{T} \mathbb{R}^4$ be given by $T\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right) = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$.

T is linear:

... (a+b) ...

T is linear:

$$T\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix} + \begin{pmatrix} e & f \\ g & h \end{pmatrix}\right) = T\left(\begin{pmatrix} a+e & b+f \\ c+g & d+h \end{pmatrix}\right) = \begin{pmatrix} a+e \\ b+f \\ c+g \\ d+h \end{pmatrix} = T\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right) + T\left(\begin{pmatrix} e & f \\ g & h \end{pmatrix}\right),$$
$$T\left(r \cdot \begin{pmatrix} a & b \\ c & d \end{pmatrix}\right) = T\left(\begin{pmatrix} ra & rb \\ rc & rd \end{pmatrix}\right) = \begin{pmatrix} ra \\ rb \\ rc \\ rd \end{pmatrix} = r T\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right)$$

Im(T):

Say $l = \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \in \mathbb{R}^4$, then $T\left(\begin{pmatrix} x & y \\ z & w \end{pmatrix}\right) = l$, therefore $\text{Im } T = \mathbb{R}^4$.

Ker(T):

$$\text{Say } T\left(\begin{pmatrix} a & b \\ c & d \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow a=b=c=d=0 \Rightarrow \begin{pmatrix} a & b \\ c & d \end{pmatrix} = 0$$

$$\text{So, } \text{Ker } T = \{0\}.$$

4) Let V be a finite dimensional vector space over \mathbb{F} and $\mathcal{B} = \{\vartheta_1, \dots, \vartheta_n\}$ be a basis of V . Define a map

$$[\]_{\mathcal{B}}: V \rightarrow \mathbb{F}^n$$

$$\text{by } [\vartheta]_{\mathcal{B}} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}, \text{ where } \vartheta = c_1 \vartheta_1 + \dots + c_n \vartheta_n \text{ for unique } c_1, \dots, c_n \in \mathbb{F}.$$

This map is called "coordinate transformation" or "a basis choice".

$[\]_{\mathcal{B}}$ is linear: Say $\vartheta = \sum c_i \vartheta_i$ and $w = \sum d_i \vartheta_i$

$$\text{then, } [\vartheta + w]_{\mathcal{B}} = \left[\sum c_i \vartheta_i + \sum d_i \vartheta_i \right]_{\mathcal{B}} = \left[\sum (c_i + d_i) \vartheta_i \right]_{\mathcal{B}} = \begin{pmatrix} c_1 + d_1 \\ \vdots \\ c_n + d_n \end{pmatrix} = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} + \begin{pmatrix} d_1 \\ \vdots \\ d_n \end{pmatrix} = [\vartheta]_{\mathcal{B}} + [w]_{\mathcal{B}}$$

$$= \sum_{i=1}^n (c_i + d_i) v_i \Big|_{\mathcal{B}} = \begin{pmatrix} c_1 + d_1 \\ \vdots \\ c_n + d_n \end{pmatrix} = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} + \begin{pmatrix} d_1 \\ \vdots \\ d_n \end{pmatrix} = [v]_{\mathcal{B}} + [w]_{\mathcal{B}}$$

$$[\lambda \cdot v]_{\mathcal{B}} = \begin{pmatrix} \lambda c_1 \\ \vdots \\ \lambda c_n \end{pmatrix} = \lambda \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} = \lambda [v]_{\mathcal{B}}$$

Im $([]_{\mathcal{B}})$: for any $\begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} \in \mathbb{F}^n$, we have

$[v]_{\mathcal{B}} = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$ for a some $v = \sum_{i=1}^n c_i v_i$, and since every vector is uniquely written as a sum of basis vectors, $\text{Im}([]_{\mathcal{B}}) = \mathbb{F}^n$ and $[]_{\mathcal{B}}$ is a bijection.

Def: Linear transformation that is a bijection is called an isomorphism of vector spaces.

Suppose $T: V \rightarrow W$ is an isomorphism of vector spaces. Since T is a bijection there exists an inverse map $T^{-1}: W \rightarrow V$.

Lemma: The inverse map of a linear transformation is linear.

Proof: Exactly the same as for \mathbb{R}^n . (Exercise)

Isomorphic vector spaces are the 'same' for all intents and purposes. Example 3) above showed that any fin. dimensional vector space is isomorphic to \mathbb{F}^n , so we do not really need new theory to study general finite dimensional vector spaces (theory that studies n -tuples $\begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$ suffices). However study

that studies n -tuples $\begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$ suffices). However study of infinite dimensional vector spaces is different! (Functional analysis).

Remark: example 2) above is also just a coordinate transformation with respect to basis

$$\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\} \text{ of } \text{Mat}_{2 \times 2}(\mathbb{R}).$$

So, as vector spaces over \mathbb{R} , $\text{Mat}_{2 \times 2}(\mathbb{R})$ is the "same" as \mathbb{R}^4 (Note that as vector space, $\text{Mat}_{2 \times 2}(\mathbb{R})$ does not take multiplication of matrices into account).

Properties of isomorphisms

- a. A linear transformation T from V to W is an isomorphism if (and only if) $\ker(T) = \{0\}$ and $\text{im}(T) = W$.

In parts (b) through (d), the linear spaces V and W are assumed to be finite dimensional.

- b. The linear space V is isomorphic to W if (and only if) $\dim(V) = \dim(W)$.
- c. Suppose T is a linear transformation from V to W with $\ker(T) = \{0\}$. If $\dim(V) = \dim(W)$, then T is an isomorphism.
- d. Suppose T is a linear transformation from V to W with $\text{im}(T) = W$. If $\dim(V) = \dim(W)$, then T is an isomorphism.

Proof: a) Say $T: V \rightarrow W$ is an isomorphism. Then T in particular is an injection, so if $T(v) = 0 = T(0)$ then $v = 0$. Therefore $\ker T = \{0\}$; also, T is

then $v=0$. Therefore $\ker T = \{0\}$; also, T is surjective, and thus $\operatorname{Im} T = W$.

Say, $\ker T = \{0\}$ and $\operatorname{Im} T = W$. Since $\operatorname{Im} T = W$ T is surjective. If $T(v) = T(w)$ then $T(v) - T(w) = 0 \Rightarrow T(v-w) = 0 \Rightarrow$ by $\ker T = \{0\}$, $v-w = 0 \Rightarrow v = w$. Thus T is an isomorphism.

b) Say $T: V \rightarrow W$ is an isomorphism. By rank-nullity $\dim V = \dim(\ker T) + \dim(\operatorname{Im} T) = 0 + \dim W = \dim W$

Conversely, say $\dim V = \dim W = n$. Then V is isomorphic to \mathbb{F}^n and W is also isomorphic to \mathbb{F}^n . Say respective isomorphisms are L and T .

$L: V \rightarrow \mathbb{F}^n$ and $T: W \rightarrow \mathbb{F}^n$. But then $V \xrightarrow{L} \mathbb{F}^n \xrightarrow{T^{-1}} W$ is an isomorphism from V to W . (Composition of isomorphisms is isomorphism in CE).

c) We showed that T is injective. We have to show that $\operatorname{Im}(T) = W$ or equivalently, $\dim(\operatorname{Im} T) = \dim W$.
by rank-nullity for $T: V \rightarrow W$

$$\dim(W) = \dim(V) = \dim \ker T + \dim \operatorname{Im} T = \dim \operatorname{Im} T$$

d) By a) it suffices to show $\ker T = \{0\}$. We conclude by rank-nullity.

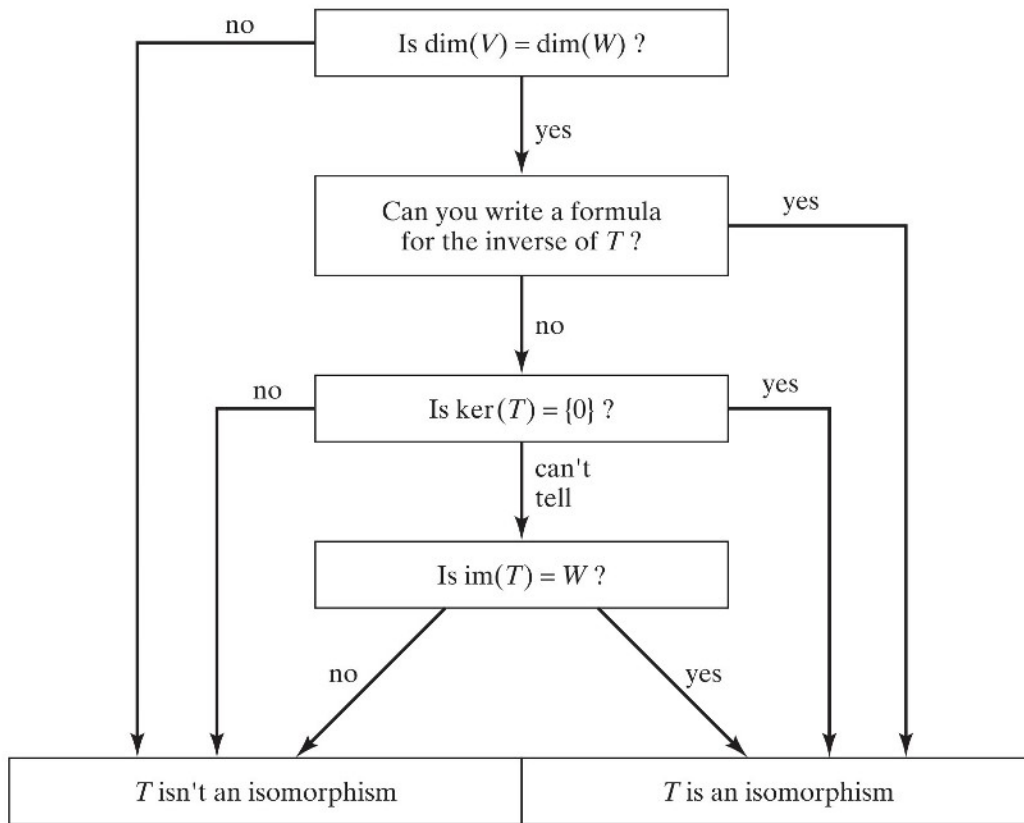


Figure 1 Is the linear transformation T from V to W an isomorphism? (V and W are finite dimensional linear spaces.)

Matrix of a linear transformation

Given two fin. dim. vector spaces V and W over \mathbb{F} and a linear transformation $T: V \rightarrow W$, we can consider

$$\begin{array}{ccc}
 V & \xrightarrow{T} & W \\
 \cong \uparrow L_1^{-1} & & \cong \downarrow L_2 \\
 \mathbb{F}^n & \xrightarrow{A} & \mathbb{F}^m
 \end{array}$$

Where $A(\vec{x}) := L_2(T(L_1^{-1}(\vec{x})))$, L_1 and L_2 are coordinate transformations. Since A is a composition of linear maps, it is itself a linear

composition of linear maps, it is itself a linear map and thus is an $m \times n$ matrix. To find this matrix A , we have to compute what it does on vectors $\begin{pmatrix} 1 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}, \dots, \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}$ and collect these in columns. But

$$A \begin{pmatrix} 1 \\ \vdots \\ 0 \end{pmatrix} = L_2 T L_1^{-1} \begin{pmatrix} 1 \\ \vdots \\ 0 \end{pmatrix} = L_2 T(\sigma_1) = [T(\sigma_1)]_{\mathcal{B}_W}$$

$$A \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix} = [T(\sigma_2)]_{\mathcal{B}_W}, \dots, A \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix} = [T(\sigma_n)]_{\mathcal{B}_W}$$

where $\mathcal{B}_V = (\sigma_1, \sigma_2, \dots, \sigma_n)$ is a V -basis corresponding to L_1 , and \mathcal{B}_W is a W -basis corresponding to L_2 . In other words

$$A = \begin{pmatrix} | & & | \\ [T(\sigma_1)]_{\mathcal{B}_W} & \dots & [T(\sigma_n)]_{\mathcal{B}_W} \\ | & & | \end{pmatrix}$$

A is called a $\mathcal{B}_V - \mathcal{B}_W$ matrix of linear map T . and

$$T(\sigma) = L_2(A(L_1(\sigma)))$$

for all $\sigma \in V$.

Example: Let $V = \text{span}(\cos(x), \sin(x)) \subseteq C^\infty$,
 C^∞ denotes \dots // // // $\mathbb{R} \rightarrow \mathbb{R}$ x-axis

Example. Let $V = \{f(x) = a \cos x + b \sin x \mid a, b \in \mathbb{R}\}$, where C^∞ denotes all functions $\mathbb{R} \rightarrow \mathbb{R}$ that are infinitely differentiable. So, $V = \{a \cos x + b \sin x \mid a, b \in \mathbb{R}\}$. Consider the transformation $T: V \rightarrow V$ given by $T(f) = 3f + 2f' - f''$.

We know that T is linear. We would like to find matrix A of T with respect to basis $(\cos x, \sin x)$. Now, on basis elements

$$\begin{aligned} T(\cos x) &= 3 \cos x - 2 \sin x + \cos x \\ &= 4 \cos x - 2 \sin x \end{aligned}$$

$$\begin{aligned} T(\sin x) &= 3 \sin x + 2 \cos x + \sin x \\ &= 2 \cos x + 4 \sin x \end{aligned}$$

So, we have that

$$A = \begin{pmatrix} \overset{T(\cos x)}{4} & \overset{T(\sin x)}{2} \\ -2 & 4 \end{pmatrix} \begin{matrix} \cos x \\ \sin x \end{matrix}$$

Q: Is T an isomorphism? Since $T = L_1 A L_1^{-1}$ and L_1 is an isomorphism, then T is an isomorphism if and only if A is, which happens if and only if matrix A is invertible, which happens if and only if $\det A \neq 0$.

So, $\det A = 4 \cdot 4 + 2 \cdot 2 = 20 \neq 0$. Therefore

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So, $\det A = 4 \cdot 4 + 2 \cdot 2 = 20 \neq 0$. Therefore
T is an isomorphism.